

Geographic Information Systems

ESM 263 - Winter 2023

Raster Data

Vector Data Review

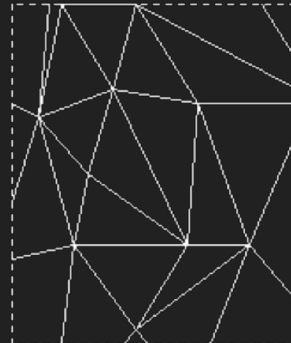
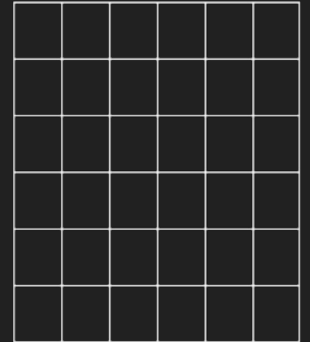
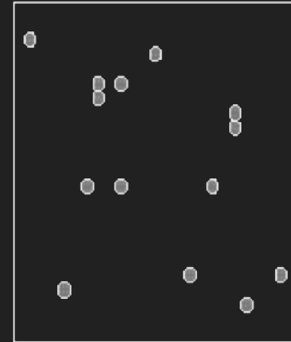
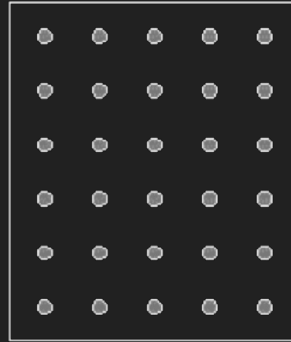
- discrete objects
- geometry = points
 - by themselves
 - connected → lines
 - closed → polygons
- attributes linked to feature ID
- explicit location
 - every point has coordinates

Fields in GIS

- continuous $f(x, y)$
- so how represent
 - Geometry?
 - Attributes?
 - Location?

Approximating Fields

- Point set
 - Regular
 - Irregular
 - Grid
- Polygons
- TIN
- Contours

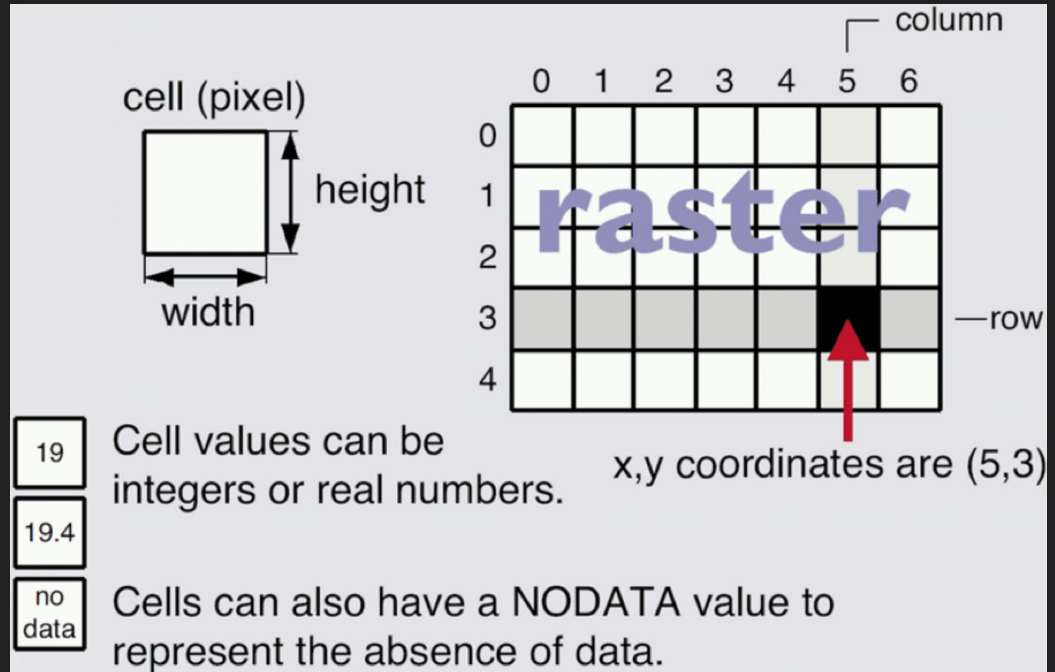


Sampled Fields: Rasters

- Divide (part of) the world into square cells (aka pixels)
- Register the corners to the Earth
- Represent fields
by assigning field values to cells
- Represent discrete objects
as collections of one or more cells
- More commonly used to represent fields
than discrete objects

Raster Data Model

- Cell size defines level of spatial detail
 - all variation within cells is lost
 - $\downarrow \rightarrow \uparrow \# \text{cells} \rightarrow \uparrow \text{data volume}$
- Cell value (field value w/in cell)
 - average? total? Modal?
 - central point?
- Implicit geometry
 - grid cell (pixel) coordinates



Raster Coordinates

- Convert raster (row, column) to map (x, y) using affine transform
- transform parameters may be saved in “world file”
 - or embedded in raster formats like GeoTIFF

$$x' = Ax + By + C$$
$$y' = Dx + Ey + F$$

display units: pixels

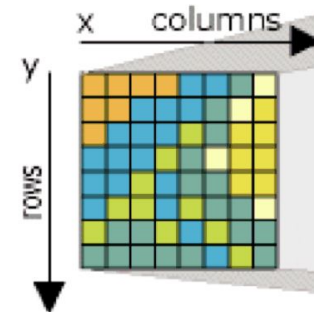
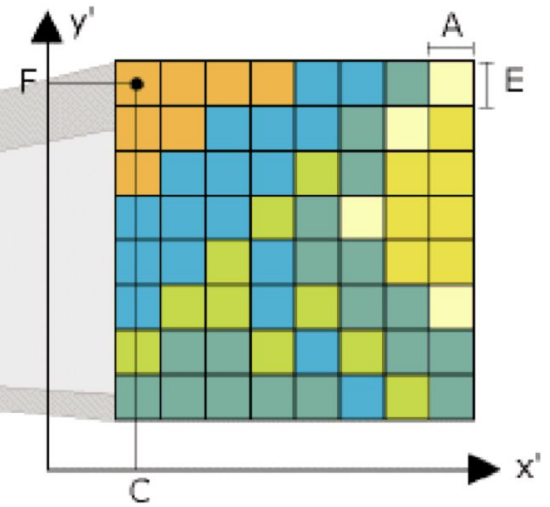


Image space

map units: meters, feet, other



Coordinate space

x is column count in image space.

y is row count in image space.

x' is horizontal value in coordinate space.

y' is vertical value in coordinate space.

A is width of cell in map units.

B is a rotation term.

C is the x' value of the center of the upper-left cell.

D is a rotation term.

E is negative height of cell in map units.

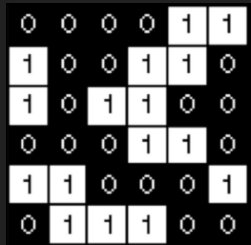
F is the y' value of the center of the upper-left cell.

Characteristics of Rasters (cont'd)

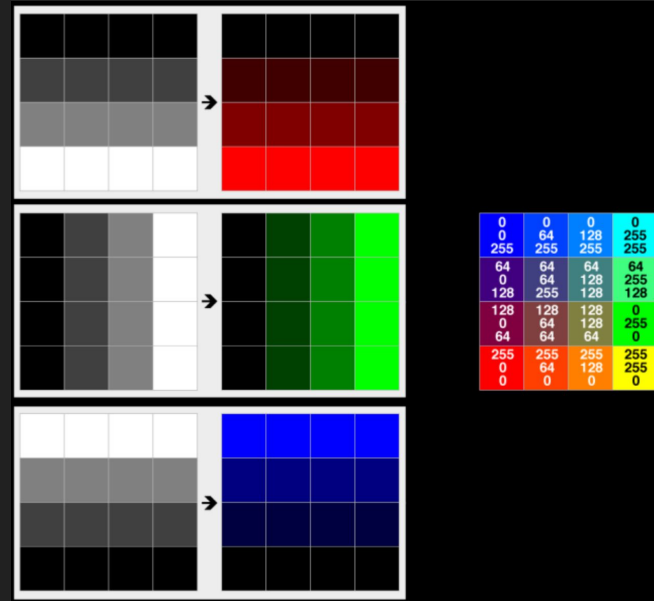
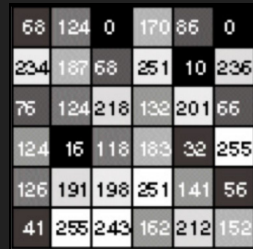
Bands (channels)

- multiple

- single ("binary")



- single ("grayscale")

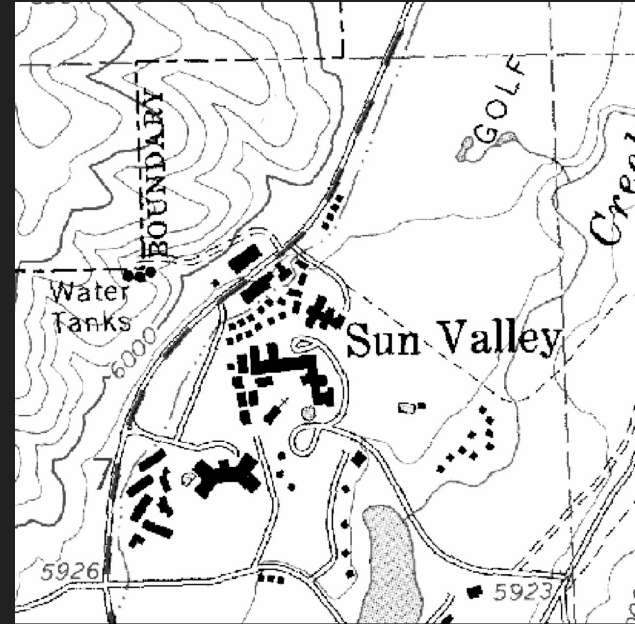


Raster Examples

aerial image

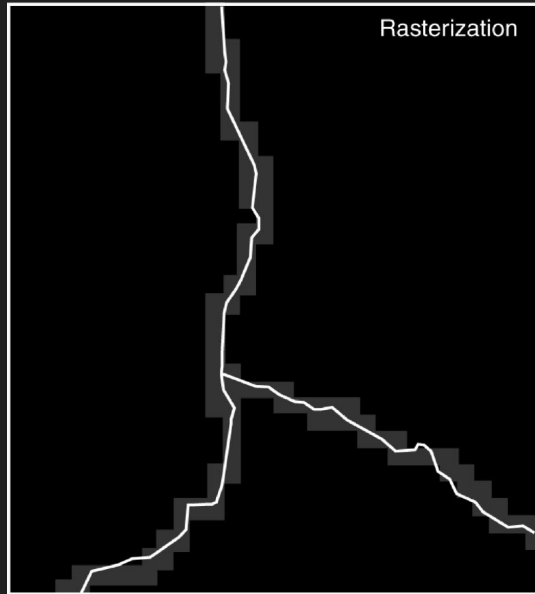


scanned topo map

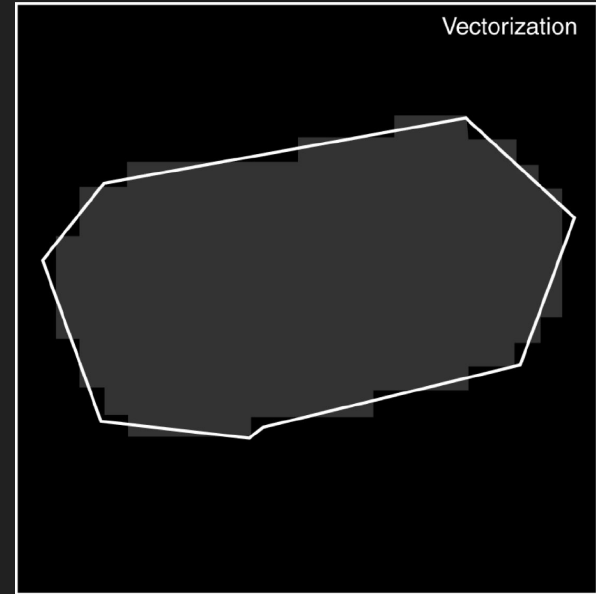


Vector \leftrightarrow Raster Conversion

Rasterize = cells that intersect feature

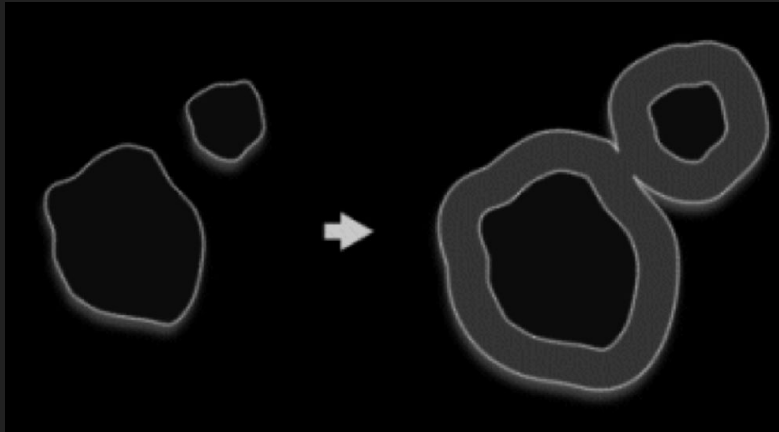


Vectorize = outline contiguous region

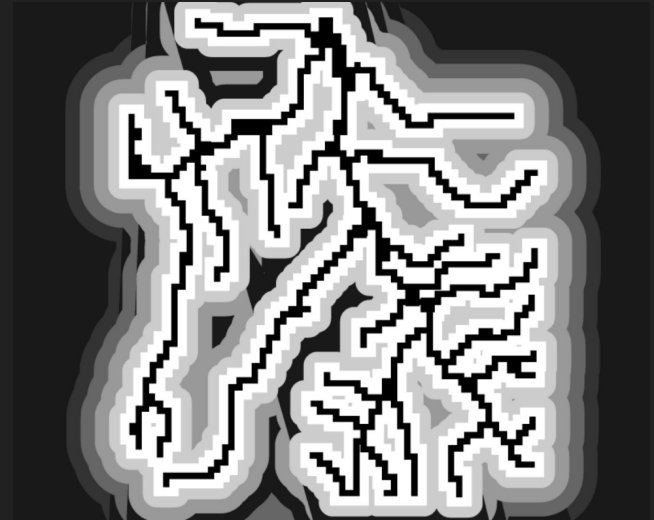


Note: Distance vs Buffering

Buffer: discrete



Distance: continuous

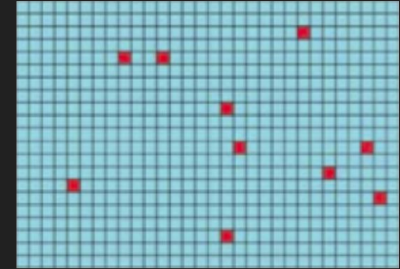
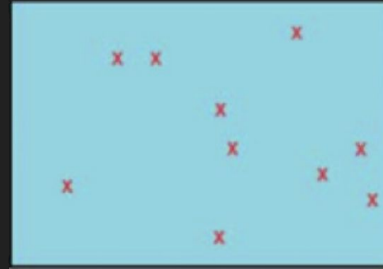


Feature Representation in Rasters: Sub-pixel Features Coarsened

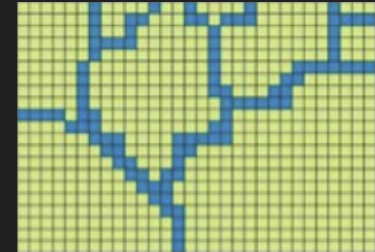
Vector

Raster

Point



Line

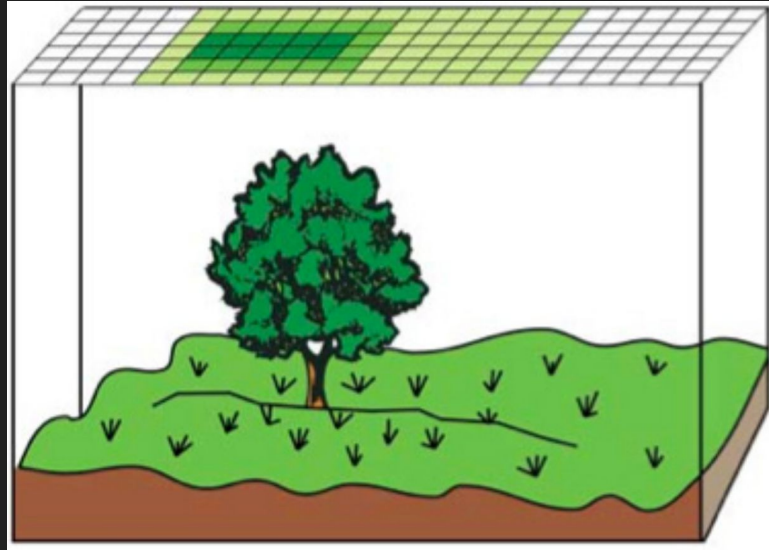


Polygon



Feature Representation in Rasters: Large Features Blurred

Tree represented as varying values of “treeness”, instead of as a crisp feature



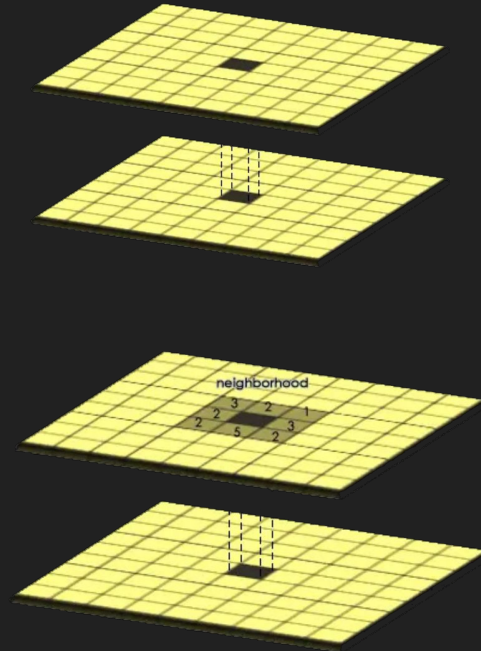
Raster Operations

in order of increasing #input cells contributing to 1 output cell

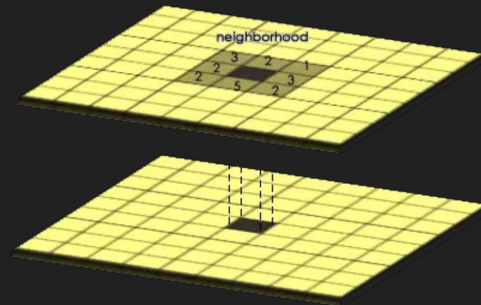
- Local
- Focal
 - aka neighborhood
- Zonal
- Global

Raster Operations

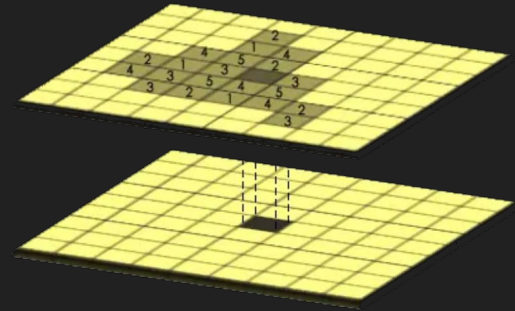
Local



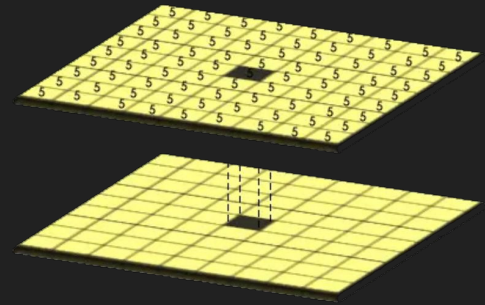
Focal



Zonal



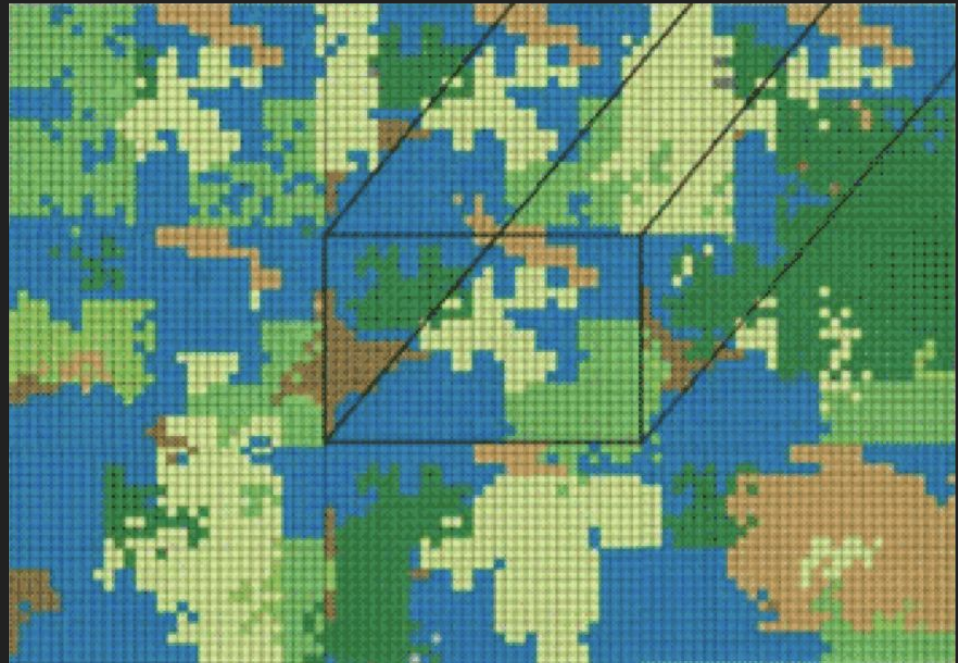
Global



Extent

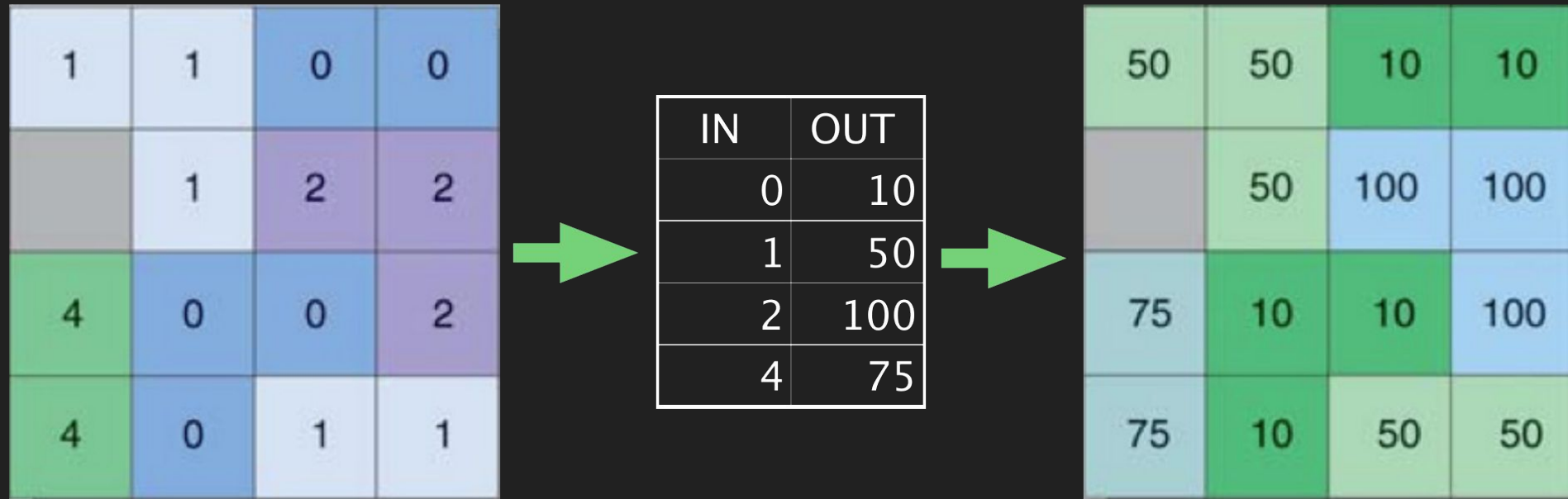
restrict processing to
rectangular subset

- explicit:
(xmin, ymin, xmax, ymax)
- default: bounding box of
inputs

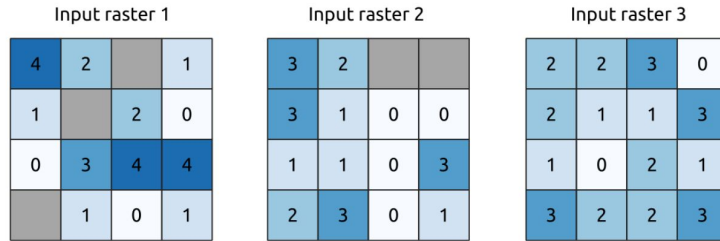


Local Operation Example: 1 Input

Reclassify (change values using lookup table)

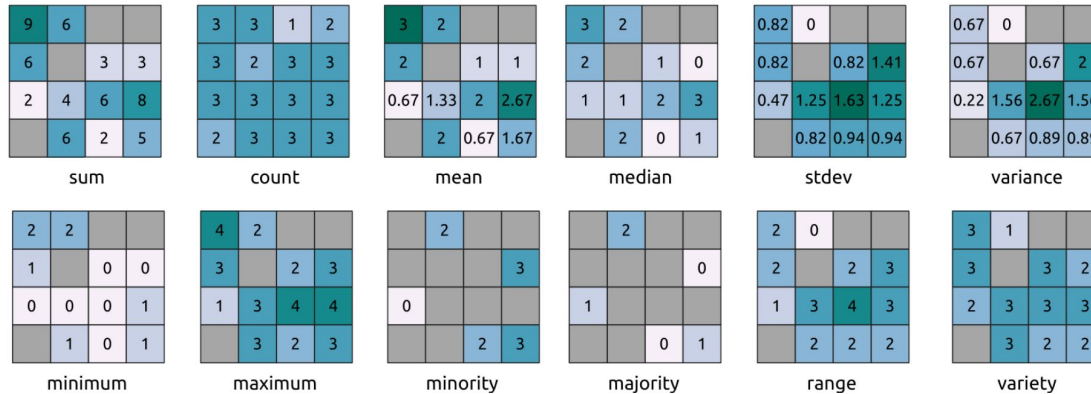


Local Operation Example: Multiple Inputs

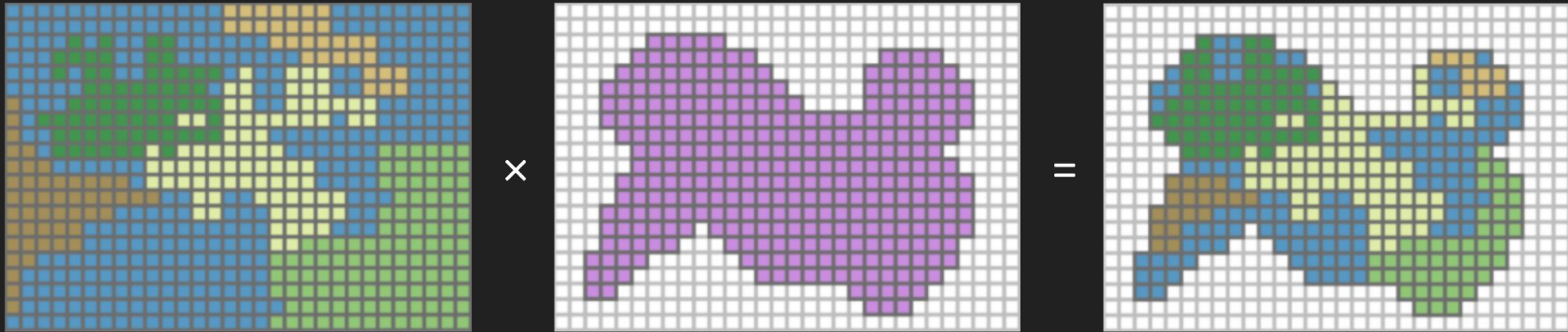


shaded = NoData

NB: NoData in any input
→ NoData in output

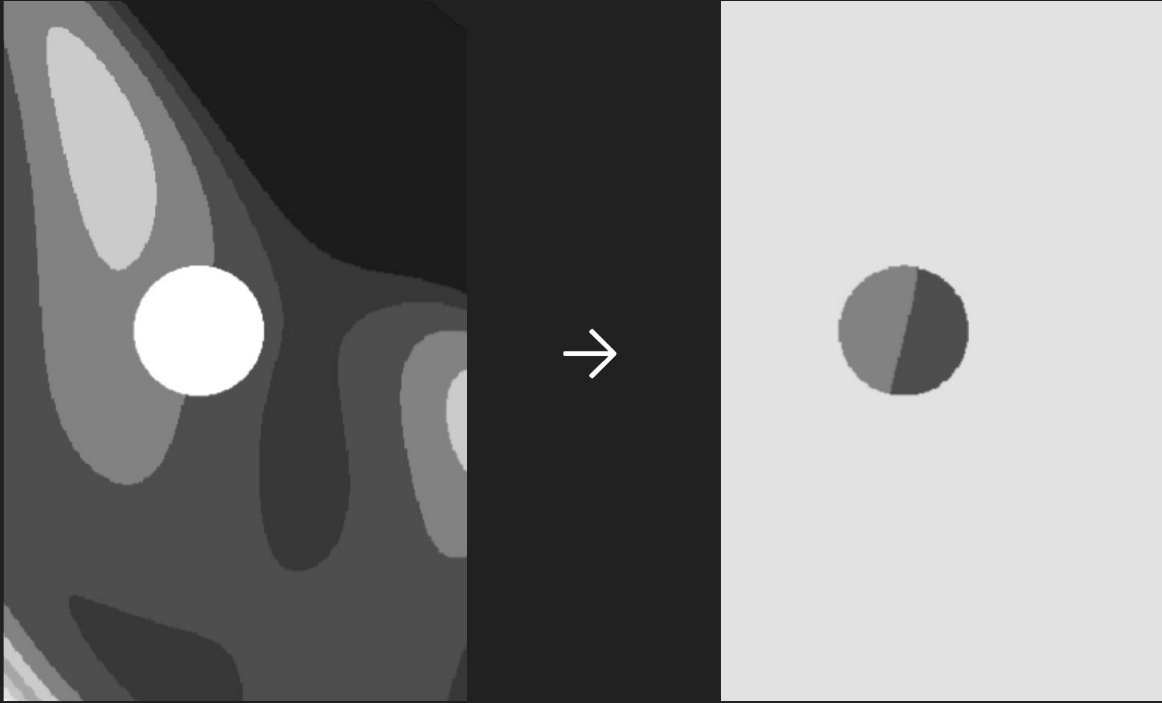


Local Operation Example: Mask



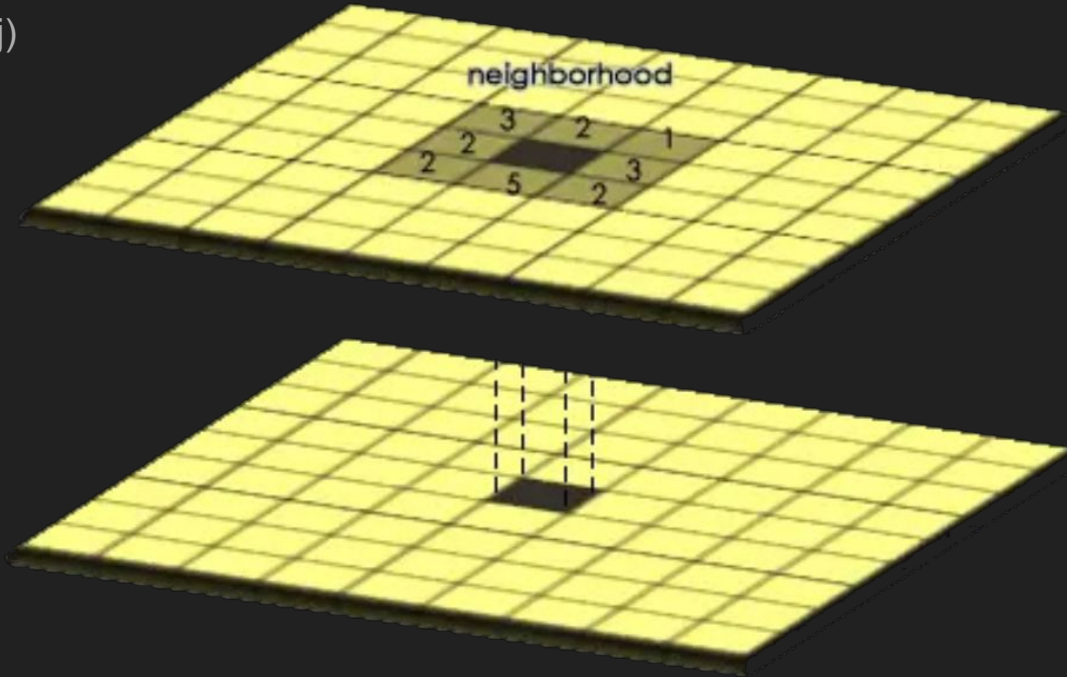
- 1 → pass
- 0 → 0
- NoData → NoData

Extract (Clip raster by mask layer (vector))



Focal (Neighborhood) Operations

- $out(x_i, y_j) = f(in(x_k, y_m) \forall k, m \text{ near } i, j)$
 - single cell and its neighbors
- Examples
 - Smooth (sharpen)
 - Noise suppression
- Think of as
 - Weighted sum or sort and pick



Focal Operation Example: Mean

$b = 3 \times 3 \text{ mean}(a)$

e.g. $(2+2+2+2+1+3+2+2+3) / 9 = 2.11$

(a)

1	2	2	2	2
1	2	2	2	3
1	2	1	3	3
2	2	2	3	3
2	2	2	2	3

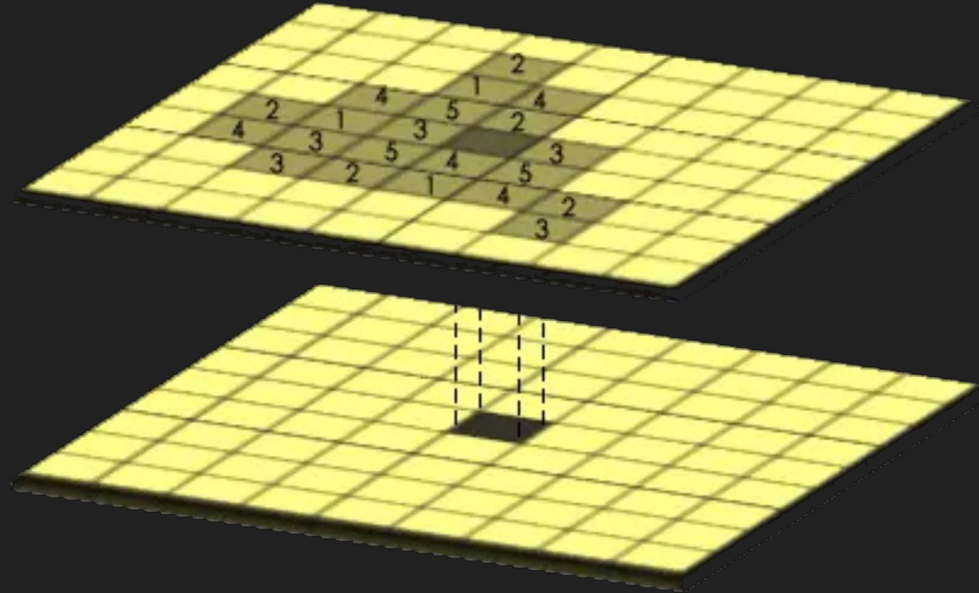
(b)

1.56	2.00	2.22
1.67	2.11	2.44
1.67	2.11	2.44

Zonal Operations

$out(x_i, y_j) =$
 $f(in(x_k, y_m) \forall k,m \exists zone(x_k, y_m) = zone(x_i, y_j))$

- like focal, but uses zone for neighborhood
- replace cell value with some property of its neighbors in zone it overlaps



Zonal Operation Example: Zonal Mean

1	2	2	1
1	4	5	1
2	3	7	6
1	3	4	4

Input

1	1	2	2
1	1	2	2
1	1	3	3
3	3	3	3

zones

2.17	2.17	2.25	2.25
2.17	2.17	2.25	2.25
2.17	2.17	4.17	4.17
4.17	4.17	4.17	4.17

zonal mean (input,zones)

e.g. $2.17 = \text{mean}(\text{zone 1: } \{1, 2, 1, 4, 2, 3\})$

Zones Can Be Discontiguous

Zone = all cells with same value

2	1	4	4	4	1
2	2	1	5	5	1
2	2	1	5	5	1
1	2	4	1	2	1
3	3	3	1	2	1
1	1	3	4	4	4

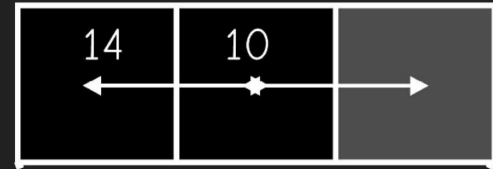
Zonal Operations in QGIS

- supported statistics
 - majority, median, minority
 - maximum, range, minimum
 - sum, mean, standard deviation
 - count, variety (# distinct values)
- zonal operations produce tables, not rasters
 - row = zone
 - column = statistic
- input zones can be a vector layer
 - output is a vector layer with zonal stats added to attribute table

Global Operations: Proximity

Euclidean distance to nearest target value(s)

$$\text{distance} = \sqrt{(x^2 + y^2)}$$



28	20	10	10	20
20	14	10	10	20
10	10	10	10	20
10	14	22		
10	10	14	22	28
10	20	22	28	36

distance from nearest
target cell

10
units

Figure Credits

- ArcGIS 9: Using ArcGIS Spatial Analyst
- ArcMap Help
- Geographic Information Systems and Science, 2nd ed. ISBN 978-0470870013
- GIS Fundamentals, 6th ed. ISBN 978-1-59399-552-2
- GISGeography.com
- Introduction to Geographic Information Systems, 4th ed. ISBN 978-0-07-305115-2
- Modeling Our World. ISBN 1-879102-62-5